### Section 1.2: Row Reduction and Echelon Forms

### Echelon form (or row echelon form):

- 1. All nonzero rows are above any rows of all zeros.
- 2. Each *leading entry* (i.e. left most nonzero entry) of a row is in a column to the right of the leading entry of the row above it.
- 3. All entries in a column below a leading entry are zero.

#### **EXAMPLE:** Echelon forms

Reduced echelon form: Add the following conditions to conditions 1, 2, and 3 above:

- 4. The leading entry in each nonzero row is 1.
- 5. Each leading 1 is the only nonzero entry in its column.

# **EXAMPLE** (continued):

Reduced echelon form:

$$\begin{bmatrix}
0 & 1 & * & 0 & 0 & * & * & 0 & 0 & * & * \\
0 & 0 & 0 & 1 & 0 & * & * & 0 & 0 & * & * \\
0 & 0 & 0 & 0 & 1 & * & * & 0 & 0 & * & * \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & * & * \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & * & *
\end{bmatrix}$$

# Theorem 1 (Uniqueness of The Reduced Echelon Form):

Each matrix is row-equivalent to one and only one reduced echelon matrix.

### **Important Terms:**

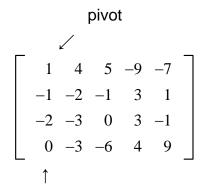
- pivot position: a position of a leading entry in an echelon form of the matrix.
- **pivot:** a nonzero number that either is used in a pivot position to create 0's or is changed into a leading 1, which in turn is used to create 0's.
- **pivot column:** a column that contains a pivot position.

(See the Glossary at the back of the textbook.)

**EXAMPLE:** Row reduce to echelon form and locate the pivot columns.

$$\begin{bmatrix}
0 & -3 & -6 & 4 & 9 \\
-1 & -2 & -1 & 3 & 1 \\
-2 & -3 & 0 & 3 & -1 \\
1 & 4 & 5 & -9 & -7
\end{bmatrix}$$

#### **Solution**



pivot column

$$\begin{bmatrix}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 5 & 10 & -15 & -15 \\
0 & -3 & -6 & 4 & 9
\end{bmatrix}$$
 Possible Pivots:

$$\left[\begin{array}{ccccccc}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & -5 & 0
\end{array}\right] \sim \left[\begin{array}{cccccccc}
1 & 4 & 5 & -9 & -7 \\
0 & 2 & 4 & -6 & -6 \\
0 & 0 & 0 & -5 & 0 \\
0 & 0 & 0 & 0 & 0
\end{array}\right]$$

Original Matrix: 
$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$
pivot columns: 
$$1 \quad 2 \qquad 4$$

Note: There is no more than one pivot in any row. There is no more than one pivot in any column.

**EXAMPLE:** Row reduce to echelon form and then to reduced echelon form:

Solution:

$$\begin{bmatrix} 0 & 3 & -6 & 6 & 4 & -5 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 3 & -9 & 12 & -9 & 6 & 15 \end{bmatrix} \sim \begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 3 & -7 & 8 & -5 & 8 & 9 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{bmatrix} \sim \begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 2 & -4 & 4 & 2 & -6 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{bmatrix}$$

Cover the top row and look at the remaining two rows for the left-most nonzero column.

$$\begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 2 & -4 & 4 & 2 & -6 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{bmatrix} \sim \begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 3 & -6 & 6 & 4 & -5 \end{bmatrix} \sim \begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 1 & -2 & 2 & 1 & -3 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$
(echelon form)

# Final step to create the reduced echelon form:

Beginning with the rightmost leading entry, and working upwards to the left, create zeros above each leading entry and scale rows to transform each leading entry into 1.

#### **SOLUTIONS OF LINEAR SYSTEMS**

- basic variable: any variable that corresponds to a pivot column in the augmented matrix of a system.
- free variable: all nonbasic variables.

#### **EXAMPLE:**

**Final Step in Solving a Consistent Linear System:** After the augmented matrix is in **reduced** echelon form and the system is written down as a set of equations:

Solve each equation for the basic variable in terms of the free variables (if any) in the equation.

#### **EXAMPLE:**

The **general solution** of the system provides a parametric description of the solution set. (The free variables act as parameters.) The above system has **infinitely many solutions.** Why?

Warning: Use only the reduced echelon form to solve a system.

# **Existence and Uniqueness Questions**

#### **EXAMPLE:**

$$\begin{bmatrix} 3x_2 & -6x_3 & +6x_4 & +4x_5 & = -5 \\ 3x_1 & -7x_2 & +8x_3 & -5x_4 & +8x_5 & = 9 \\ 3x_1 & -9x_2 & +12x_3 & -9x_4 & +6x_5 & = 15 \end{bmatrix}$$

In an earlier example, we obtained the echelon form:

$$\begin{bmatrix} 3 & -9 & 12 & -9 & 6 & 15 \\ 0 & 2 & -4 & 4 & 2 & -6 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix} (x_5 = 4)$$

No equation of the form 0 = c, where  $c \neq 0$ , so the system is consistent.

Free variables:  $x_3$  and  $x_4$ 

Consistent system ⇒ infinitely many solutions. with free variables

### **EXAMPLE:**

Consistent system, no free variables ⇒ unique solution.

# **Theorem 2 (Existence and Uniqueness Theorem)**

1. A linear system is consistent if and only if the rightmost column of the augmented matrix is not a pivot column, i.e., if and only if an echelon form of the augmented matrix has no row of the form

$$\begin{bmatrix} 0 & \dots & 0 & b \end{bmatrix}$$
 (where  $b$  is nonzero).

- 2. If a linear system is consistent, then the solution contains either
- (i) a unique solution (when there are no free variables) or
- (ii) infinitely many solutions (when there is at least one free variable).

# Using Row Reduction to Solve Linear Systems

- 1. Write the augmented matrix of the system.
- 2. Use the row reduction algorithm to obtain an equivalent augmented matrix in echelon form. Decide whether the system is consistent. If not, stop; otherwise go to the next step.
- 3. Continue row reduction to obtain the reduced echelon form.
- 4. Write the system of equations corresponding to the matrix obtained in step 3.
- 5. State the solution by expressing each basic variable in terms of the free variables and declare the free variables.

#### **EXAMPLE:**

- a) What is the largest possible number of pivots a  $4 \times 6$  matrix can have? Why?
- b) What is the largest possible number of pivots a  $6 \times 4$  matrix can have? Why?
- c) How many solutions does a consistent linear system of 3 equations and 4 unknowns have? Why?
- d) Suppose the coefficient matrix corresponding to a linear system is  $4 \times 6$  and has 3 pivot columns. How many pivot columns does the augmented matrix have if the linear system is inconsistent?